

# DMP2042

## 2 axes LSI Pulse Generator

### Features

- 2 axes control by one chip
- Full proportional user setting acceleration/deceleration curve function which is realized by simple free setting of user image
- Automatic generating S curve acceleration/deceleration by same parameter setting with trapezoidal driving
- Buffering function which can store maximum 3 sets of driving parameter.
- Shape protection function when changing speed during driving
- Shape protection function which automatically correct contradictory parameter setting
- Speed override function
- Automated continuous interpolated driving/path driving
- Absolute/incremental count of the numbers of output pulses. Wide range managing counter.
- 32 bit encoder counter / general purpose counter of automatic bite length.
- 8bit x 8 general purpose counter with compare, available to connect bite by bite (maximum 64 bit length)
- Home search movement with Z phase counter function.

### Specification

Power voltage: 3.3V±5%

I/O level: TTL level

Standard clock: Maximum 10MHz

Range of total pulse numbers setting: 1 to 16,777,215 pulses or endless

Range of deceleration start point setting: 0 to 16,777,215 pulses

Numbers of frequency setting step: 65,536 steps

Numbers of acceleration deceleration slope setting: 65,536 steps

Numbers of output pulse gear step: 256 steps

Numbers of proportional shape slope data: 64 words

Range of output frequency :

0.004 to 256Hz (CLK=131kHz, ratio=256)

1 to 65,535Hz (CLK=3.2768MHz, ratio=25)

75 to 5,000,000Hz (CLK=10MHz, ratio=1)

**Driving and function:**

Full proportional shaped and trapezoidal acceleration deceleration driving  
Automatic generating S curve acceleration/deceleration driving  
Shape protect and guarantee function  
Buffering function  
Speed override function  
Interpolation for more than 2 axes  
Continuous interpolation function for more than 2 axes by buffering function  
Path moving  
Path moving  
Supporting 8/16bit data bus  
Supporting Intel/Motorola data format  
Supporting absolute or incremental moving distance  
Multi axes synchronous start function  
Automatic calculation of deceleration start point  
Home searching  
Encoder counter function (with interrupt function)  
8bit with comparer (proportional combination is available) x 8 general purpose counter  
Pulse generation function for motor driving from A/B phase pulse input  
Deviation discriminative function  
I/O signal logic setting function  
Forward / Reverse overrun  
Instant / decelerated stop  
Servo motor control  
Monitor for numbers of output pulses  
Setting of each acceleration / deceleration slope  
Linear interpolation movement

**Driver interface:**

Output: clock, 1/2 clock selectable, logic selectable  
Input : Alarm(logic selectable),  
In-position (logic selectable),  
Deviation counter overflow (logic selectable),

**Sensor input**

Overrun (Forward, reverse, logic selectable)

Near home (logic selectable)

Home (logic selectable)

**Encoder Interface**

Input: A/B phase, Phase 1/2/4 times, CW, CCW clock count

Output : 4 interrupt outputs

**Exclusive I/O**

Input : Deceleration, Decelerated stop, Instant stop, Synchronization

Output : During pulse output, End interrupt

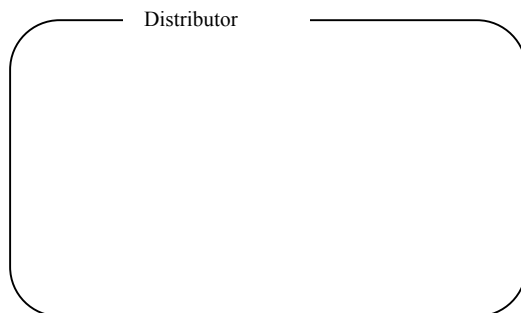
**Exclusive I/O**

Each 8 points

Operating Environment temperature : 0 to +70°C

Storing temperature : -55 to +125°C

Package: 144 pins, plastic QFP, 0.5mm lead pitch

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